

- [013]** The ability to transmit clutch power is proportional to the pressure supply of the pressure chamber, i.e. the volume available between bell F, drive shaft E and piston L. ⇨
- [014]** This pressure also determines actuation times. If during the approximation phase a pressure level equivalent to that of the return spring G is reached, this will cause the piston L to remain in a state of equilibrium - its ~~approximation~~ approximation speed will therefore be 0 while its approximation time becomes infinite. On the other hand, if pressure reaches a “very high” level, the actuation time can drop to a minimum value. ⇨
- [015]** Hobby skippers generally believe that the response time of a boat to course change ~~com-mands~~ commands should be reduced as much as possible. The ideal response time would be 0. ⇨
- [016]** The clutch contributes to the response time, but it is not the only component on which ~~re-sponse~~ response time depends. Ergonomics of control and the integrity of the engine/propeller drive train prohibit ~~influ-encing~~ influencing ramp time and force us to influence the approximation time. A number of solutions are available for this: Optimization/enlargement of the cross-section of lines leading from the pump M to the clutch; use of a different oil grade with different physical properties; modification of the delivery volume during the approximation phase; modification of the “displacement” of the clutch (either by reducing the cross-section of the piston in favor of a proportional increase in operating pressure or by reducing the ~~assem-~~ assembly clearance of the clutch package); splitting of clutch “displacement” into two sections ( a first one with a smaller cross-section for a faster acceleration phase and a second one with a cross-section equivalent to the rated cross-section); ⇨

elevation of the minimum ~~pres-sure~~ pressure level (in a traditional actuation system ⇨  
this reduces approximation time but increases the likelihood for jerks within the drive  
train during the actuation phase); use of the ECU together with the proportional  
solenoid vales O and P.

**[017]** All these solutions - which can also be combined - have their limitations, due ⇨  
to the high expenses involved, but also because of the fact that they require the  
application of use specific solutions and the resulting difficulties involved in precise,  
detailed adjustment.

**[018]** SUMMARY OF THE INVENTION ⇨

**[019]** The main object of the present invention is to use a simple but at the same ⇨  
time extremely efficient approach to produce a device that permits optimization of  
hydraulically controlled engagement of clutches used in marine transmissions and  
also allows the approximation time to be reduced, by means of which above  
problems can be counteracted. With regard to this main object, one purpose of the  
present invention is to produce a ~~de-vice~~ device capable of automatic auto-control ⇨  
as far as certain functional or operational ~~parameters~~ parameters(e.g. operating ⇨  
temperature and delivery volume, which can vary in relation to the ~~ro-tation~~ rotation ⇨  
speed of the pump) are concerned.

**[020]** These objectives and other ones to be detailed in the following can be ⇨  
achieved by means of a device for the optimization of hydraulically controlled  
engagement of clutches used in marine transmissions and comprising pumps for  
delivering hydraulic fluid to two control pistons of said clutches, two solenoid valves  
arranged between said pumps and said ~~pis-tons~~ pistons, a bistable valve arranged ⇨

in parallel between said solenoid valves and said pistons, a control valve arranged on the pressure side of said pumps towards the discharge line leading to the reservoir and equipped with an adjusting device, whose spring element is linked to said bistable valve, whereby said device for the optimization of engagement is characterized in that it comprises a shuttle-type sequence valve for the link between the spring element of said adjusting device and the supply line of said solenoid valves or said bistable sequence valve, whereby the bistable valve is also linked to the hydraulic control of said sequence valve, and whereby a preset pressure drop is produced between the spring element of said adjusting device and said bistable valve, and said adjusting device is linked to the pressure side of said pumps.

## [021] BRIEF DESCRIPTION OF THE DRAWINGS

**[022]** Further attributes and advantages of the present invention can largely be inferred from the detailed description of one of its implementations, which is shown in the attached sketches and is not subject to any limitations with regard to the scope of applications. The sketches show the following The invention will now be described, by way of example, with reference to the accompanying drawings in which:

which:

[023] Fig. 1 is a diagram of a known marine transmission.

**[024]** Fig. 2 is a sectional view of the clutch of the transmission from Fig. 1. ↩

**[025]** Fig. 3 is a hydraulic diagram of a known clutch engagement device for the clutch from Fig. 1.

**[026]** Fig. 4 is a functional diagram of the device from Fig. 3, in which the pressure curve is shown in relation to the time.

**[027]** Fig. 5 is a hydraulic diagram according to the present invention. ⇄

**[028]** Fig. 6 is as diagram of an implementation of one of the components of the device from Fig. 5. ⇄

**[029]** Fig. 7 is a functional diagram of the device from Fig. 5, in which the pressure curve is shown in relation to the time. ⇄

**[030]** DETAILED DESCRIPTION OF THE INVENTION ⇄

**[031]** With reference to above mentioned illustrations (Fig. 5 to Fig. 7), a device for the ~~optimi-za-tion~~ optimization of hydraulically controlled engagement of clutches used in marine transmissions ~~com-prises~~ comprises a pump 10 for delivering hydraulic fluid from a reservoir 11 to two control ~~pis-tons~~ pistons 12a and 12b of said clutches - one for forward drive and one for reverse drive control. ⇄

**[032]** Two solenoid valves (13/14) arranged between the pump 10 and between the piston 12a or 12b, the selector valve 13 for forward drive and the discharge into the reservoir 11 and the selector valve 14 for reverse drive and the discharge into the reservoir 11. ⇄

**[033]** A bistable valve ~~[[11]]~~ 15 is arranged in ~~parallel~~ between the solenoid valves 13 and 14 and the pistons 12a and 12b; and a control valve 16 is provided on the pressure side of the pump 10 toward the discharge into the reservoir 11 and provided with an adjusting device 17, whose spring element 18 is linked to the bistable valve 15. ⇄

**[034]** According to the invention, the device for engagement optimization is characterized in that is comprises a shuttle-type sequence valve 19 on the link between the spring element 18 and the adjusting device 17 and the supply of the ⇄

solenoid valves 13 and 14 or the ~~bistable~~ bistable valve 15. The bistable valve is also linked to the hydraulic control 20 of the sequence valve 19. ⇄

**[035]** A preset pressure drop is produced between the spring element 18 of the adjusting device 17 and the bistable valve 15, and the adjusting device 17 is linked to the pressure side of the pump 10. ⇄

**[036]** It is of advantage that the preset pressure drop produces a throttling effect, which can be brought about functionally or by means of a suitable valve 21 or by means of suitable ~~de-sign~~ design of the lines, whereby these lines cause an equivalent pressure drop. ⇄

**[037]** As for valve 21 (a function example of which is shown in Fig. 6 and which constitutes a check valve with hydraulic control for both directions of flow), which is connected in ~~par-allel~~ parallel with a throttle valve 28, this can be integrated at will in any section of the circuit marked with 22 (between the sequence valve 19 and the bistable valve 15) or marked with 23 (between the sequence valve 19 and the spring element 18 of the adjusting device 17). ⇄

**[038]** As for function, the sequence valve 19 in the condition as shown in Fig. 5 is held in ~~pos-ition~~ position (1) by the spring 24, and the adjusting device 17 is thus provided with the pressure present before the solenoid valves 13 and 14 via the lines 25 and 23. ⇄

**[039]** Consequently, a raised level of operational nominal pressure is available. In idle condition, the bistable valve 15 is linked via line 22 with valve 21 and the hydraulic control 20 of the sequence valve 19, whereby a discharge line to the reservoir 11 is created. ⇄

**[040]** If activation of one of the solenoid valves 13 or 14 is requested, then the ⇄

bistable valve 15 will supply the control 20 of the sequence valve 19 via the pressure level present in the supply line of the clutch being controlled.

**[041]** The sequence valve 19 thus changes to position (2). In the control phase the adjusting ~~de-vice~~ device 17 starts discharging some of the oil via the lines 22, 23 and valve 21 toward the clutch. ⇄

**[042]** In this phase, the pressure controlled by the control valve 16 drops from the operational nominal value to the minimum value. When the approximate value is reached, a state of equilibrium is established between the pressure on the link 23 to the adjusting device 17 and the pressure on the link 22 to the bistable valve, whereby piston 26 inside the control valve 16 is in fully retreated position (position x). The pressure available is equivalent to the minimum pressure. ⇄

**[043]** Consequently, identical standard functional conditions are present at the onset of the ~~en-gagement~~ engagement phase of the clutches. Hereby, the direction of flow of the oil passing through vale 21 is reversed and the oil from the bistable valve 15 feeds the adjusting device 17, which (precisely as described before) permits a constant increase in the pressure level within the circuit. This allows smooth and progressive engagement of the clutch. ⇄

**[044]** An outstanding feature of the device is its auto-control capability with regard to preset ~~op-erating~~ operating or functional parameters (e.g. operating temperature and delivery volume, which can vary in relation to the rotation speed of the pump 10) which affect pressure drops in the section after the control valve 16 and before the solenoid valves 13 and 14. ⇄

**[045]** In the present design, this capability is realized by means of a suitable design of the ~~pis-ton~~ piston of valve 16 in the form of several diameters. Introduction of a ⇄

test valve 27 (together with the sequence valve 19 and valve 21, which corresponds to a throttle), which during the approximation phase provides a pressure level above the minimum pressure level and equivalent to the minimum level at the end of the approximation phase and which monitors the subsequent ramp, makes it possible to ~~counteract~~ counteract the problems encountered by means of a simple and at the same time extremely efficient solution. ⇨

**[046]** With reference to the diagram from Fig. 7, the test valve 27 in practical application uses the following parameters (in terms of pressure values): ⇨

- pressure in the pump 10;
- pressure before the solenoid valves 13 and 14;
- pressure after the solenoid valves 13 and 14;

and via the control of the control valve 16 provides a pressure level (on the solenoid valves 13 and 14 and thus on the associated piston 12a and 12b) which constantly drops, starting at the onset of the approximation phase (point 1 of the diagram) and until the minimum ~~pres-sure~~ pressure level is reached at the end of the approximation phase (point 2 of the diagram). ⇨

**[047]** Comparison of the diagram from Fig. 4 with the known devices shows that the referenced point 2 is reached at an earlier time compared to the corresponding point 2. As already explained, this pressure increase permits reduction of the approximation time. In this point, valve 27 permits initiation of the preset standard ramp. Introduction of valve 27 combined with control valve 16 permits neutralization of the ~~ef-fects~~ effects of changes of temperature and oil flow rate (versus the approximation time) by means of an automatic control mechanism. The principles of ergonomics of clutch actuation are not affected. ⇨

**[048]** The method reverses the previous concept, since the control phase starts under ~~operational~~ operational pressure, the minimum pressure level is reached at the end of the piston travel of piston 12a or 12b (approximation point), and subsequently the capacity is increased to transmit a gradual elevation in pressure until the operational pressure has been restored.

**[049]** Practical application has shown how the present invention permits a satisfactory solution to be found for the main objective and for the targets set to achieve this objective.

**[050]** The invention can be subjected to a variety of modifications; they are, however, all within the conceptual framework of the invention.

**[051]** Moreover, all single parts can be exchanged with equivalent technical components.

The materials used can be freely chosen according to requirements, provided they ~~con-form~~ conform to the specified application and dimensions.